

Leveraging Labeled and Unlabeled Data for Consistent Fair Binary Classification (NeurIPS 2019)

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September 28, 2025

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Introduction

Notations

- $X \in \mathbb{R}^d$: d -dimensional feature vector,
- $S \in \{0, 1\}$: Binary Sensitive Attribute,
- $Y \in \{0, 1\}$: Binary Label,
- $g : \mathbb{R}^d \times \{0, 1\} \rightarrow \{0, 1\}$: Classifier (a measurable function),
- $\eta(x, s) := \mathbb{P}(Y = 1 \mid X = x, S = s)$: Regression Function
- $\mathcal{R}(g) := \mathbb{P}(g(X, S) \neq Y)$: Risk Function.

Problem Motivation

- ① Machine learning is widely deployed in society, but models often produce **unfair outcomes** when predictions correlate with **sensitive attributes** (e.g. gender, race).
- ② The paper focuses on **Equal Opportunity(EO) Fairness**, which requires equal True Positive Rates(TPR) across sensitive groups.

► Equal Opportunity

A classifier $g(x, s) \in \{0, 1\}$ is called fair if

$$P(g(X, S) = 1 \mid S = 1, Y = 1) = P(g(X, S) = 1 \mid S = 0, Y = 1).$$

The set of all fair classifiers is denoted by $\mathcal{F}(\mathbb{P})$.

What We Show?

Among all EO-fair classifiers $\mathcal{F}(\mathbb{P})$, which classifier minimizes the risk?

Answering the question above is equivalent to solving the following problem:

$$\min_{g \in \mathcal{F}(\mathbb{P})} \mathcal{R}(g), \quad \mathcal{R}(g) := \mathbb{P}(g(X, S) \neq Y).$$

Equivalently,

$$\min_g \mathcal{R}(g) \text{ s.t. } \mathbb{P}(g=1 \mid Y=1, S=1) = \mathbb{P}(g=1 \mid Y=1, S=0).$$

Our paper shows that the EO-optimal classifier takes the following form:

$$g^*(x, 1) = \mathbf{1}\left\{1 \leq \eta(x, 1) \left(2 - \frac{\theta^*}{\mathbb{P}(Y=1, S=1)}\right)\right\}, \quad g^*(x, 0) = \mathbf{1}\left\{1 \leq \eta(x, 0) \left(2 + \frac{\theta^*}{\mathbb{P}(Y=1, S=0)}\right)\right\}.$$

where $\theta^* \in \mathbb{R}$ is chosen to equalize the two groups' TPRs and satisfies $|\theta^*| \leq 2$.

What We Show? (continued)

We do not know the true distribution \mathbb{P} nor the oracle shift θ^* . **Our approach** estimates them *empirically* (via a plug-in scheme using labeled data for $\hat{\eta}$ and unlabeled data for $\hat{\theta}$) and then proves **consistency**:

$$\underbrace{\mathbb{E}[\Delta(\hat{g}, \mathbb{P})] \rightarrow 0}_{\text{asymptotically fair}} \quad \text{and} \quad \underbrace{\mathbb{E}[\mathcal{R}(\hat{g})] \rightarrow \mathcal{R}(g^*)}_{\text{asymptotically optimal}},$$

where $\Delta(g, \mathbb{P}) := |\mathbb{P}(g(X, S) = 1 \mid S = 1, Y = 1) - \mathbb{P}(g(X, S) = 1 \mid S = 0, Y = 1)|$.

Here, $\Delta(g, \mathbb{P})$ is what we call **Unfairness** in this paper.

Methods

Set Up

In this section, we explain *why the EO-optimal classifier takes the form* introduced earlier,

$$g^*(x, 1) = \mathbf{1}\left\{1 \leq \eta(x, 1)\left(2 - \frac{\theta^*}{\mathbb{P}(Y=1, S=1)}\right)\right\}, \quad g^*(x, 0) = \mathbf{1}\left\{1 \leq \eta(x, 0)\left(2 + \frac{\theta^*}{\mathbb{P}(Y=1, S=0)}\right)\right\}.$$

how to estimate the unknown quantities in that rule (the distribution \mathbb{P} and the shift θ^*), and *why the resulting plug-in classifier is consistent*.

► Assumption

We assume that we have at our disposal two datasets, labeled \mathcal{D}_n and unlabeled \mathcal{D}_N :

$$\mathcal{D}_n = \{(X_i, S_i, Y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} \mathbb{P}, \quad \mathcal{D}_N = \{(X_i, S_i)\}_{i=n+1}^{n+N} \stackrel{\text{i.i.d.}}{\sim} \mathbb{P}_{X,S}.$$

Notation for group counts in \mathcal{D}_N :

$$N_s := \sum_{i=n+1}^{n+N} \mathbf{1}\{S_i = s\}, \quad N := \sum_{s \in \{0,1\}} N_s \quad (s \in \{0,1\}).$$

Optimal EO Classifier Proof Sketch (1/3)

Step 1. Wrap EO into a Lagrangian. Start from

$$\min_g \mathcal{R}(g) \quad \text{s.t.} \quad \mathbb{P}(g=1 \mid Y=1, S=1) = \mathbb{P}(g=1 \mid Y=1, S=0).$$

Introduce a multiplier λ and consider the saddle problem $\min_g \max_\lambda \mathcal{L}(g, \lambda)$. By weak duality, solving $\max_\lambda \min_g \mathcal{L}(g, \lambda)$ is enough to identify the optimal form.

$$\mathcal{L}(g, \lambda) = \mathcal{R}(g) + \lambda \left(\mathbb{P}(g=1 \mid Y=1, S=1) - \mathbb{P}(g=1 \mid Y=1, S=0) \right).$$

Step 2. Linearize in g . Write both the risk and the EO term as expectations that are *linear in g* :

$$\mathcal{R}(g) = \text{const} - \sum_{s \in \{0,1\}} \mathbb{P}(S=s) \mathbb{E}_{X|S=s} [g(X, s) (2\eta(X, s) - 1)],$$

and the EO difference as $\mathbb{E}_{X|S=s} [\eta(X, s) g(X, s)] / \mathbb{P}(Y=1 \mid S = s)$. This lets us minimize $\mathcal{L}(g, \lambda)$ *pointwise* in (x, s) .

Optimal EO Classifier Proof Sketch (2/3)

Step 3. Pointwise minimization \Rightarrow threshold rule.

For each (x, s) , choose $g(x, s) \in \{0, 1\}$ that minimizes the local linear expression.

This yields, for any fixed λ ,

$$g_\lambda(x, 1) = \mathbf{1}\left\{1 \leq \eta(x, 1)\left(2 - \frac{\lambda}{\mathbb{P}(Y=1, S=1)}\right)\right\}, \quad g_\lambda(x, 0) = \mathbf{1}\left\{1 \leq \eta(x, 0)\left(2 + \frac{\lambda}{\mathbb{P}(Y=1, S=0)}\right)\right\}.$$

So the solution must be a *thresholded Bayes regressor with group-dependent shift*.

For fixed λ , $\mathcal{L}(g, \lambda)$ is linear in g . The pointwise coefficient of $g(x, s)$ equals

$$\underbrace{-(2\eta(x, s) - 1) \mathbb{P}(S=s)}_{\text{from risk}} + \underbrace{\lambda \cdot \frac{\eta(x, 1)}{\mathbb{P}(Y=1 | S=1)} \mathbf{1}\{s=1\} - \lambda \cdot \frac{\eta(x, 0)}{\mathbb{P}(Y=1 | S=0)} \mathbf{1}\{s=0\}}_{\text{from EO term}}.$$

Choose $g(x, s) = 1$ iff this coefficient ≤ 0 . For $s=1$ it reduces to

$$1 \leq \eta(x, 1)\left(2 - \lambda/\mathbb{P}(Y=1, S=1)\right); \text{ for } s=0 \text{ to } 1 \leq \eta(x, 0)\left(2 + \lambda/\mathbb{P}(Y=1, S=0)\right).$$

Optimal EO Classifier Proof Sketch (3/3)

Step 4. Pick $\lambda = \theta^*$ to satisfy EO.

Choose θ^* so that the two TPRs match:

$$\frac{\mathbb{E}_{X|S=1}[\eta(X, 1) g_{\theta^*}(X, 1)]}{\mathbb{P}(Y=1 | S=1)} = \frac{\mathbb{E}_{X|S=0}[\eta(X, 0) g_{\theta^*}(X, 0)]}{\mathbb{P}(Y=1 | S=0)}.$$

Under mild continuity, there exists a unique θ^* that equalizes the two TPRs.

Define $\phi(\lambda) := \text{TPR}_1(g_\lambda) - \text{TPR}_0(g_\lambda)$. With no mass at the threshold, ϕ is continuous and strictly monotone in λ , so by the intermediate value theorem there is a unique root.

Step 5. Conclude optimality.

At (g_{θ^*}, θ^*) we satisfy EO and attain the dual optimum. Weak duality then implies g_{θ^*} minimizes risk among all EO-fair classifiers.

Step 6. Range of θ^* .

We show

$$2 - \frac{\theta^*}{\mathbb{P}(Y=1, S=1)} > 0 \quad \text{and} \quad 2 + \frac{\theta^*}{\mathbb{P}(Y=1, S=0)} > 0,$$

hence $-2\mathbb{P}(Y=1, S=0) < \theta^* < 2\mathbb{P}(Y=1, S=1)$ and in particular $|\theta^*| \leq 2$.

Proposed Plug-in Procedure (1/2)

Regression estimator

An estimator $\hat{\eta}$ of $\eta(x, s) := \mathbb{P}(Y = 1 \mid X = x, S = s)$ is constructed from the labeled sample \mathcal{D}_n and is independent of the unlabeled sample \mathcal{D}_N (e.g., by sample splitting).

Empirical Distributions \mathcal{D}_N

For $s \in \{0, 1\}$, Define

$$\hat{\mathbb{P}}_{X|S=s} = \frac{1}{|\{(X,S) \in \mathcal{D}_N : S=s\}|} \sum_{\{(X,S) \in \mathcal{D}_N : S=s\}} \delta_X, \quad \hat{\mathbb{P}}_S = \frac{1}{N} \sum_{\{(X,S) \in \mathcal{D}_N\}} \delta_S$$

where δ_z denotes the Dirac point mass at z (i.e., the measure that assigns probability 1 to the singleton $\{z\}$ and 0 elsewhere).

Proposed Plug-in Procedure (2/2)

From the optimal-form family

$$g^*(x, 1) = \mathbf{1}\left\{1 \leq \eta(x, 1) \left(2 - \frac{\theta^*}{\mathbb{P}(Y=1, S=1)}\right)\right\}, \quad g^*(x, 0) = \mathbf{1}\left\{1 \leq \eta(x, 0) \left(2 + \frac{\theta^*}{\mathbb{P}(Y=1, S=0)}\right)\right\}.$$

the unknowns are the joint terms $\mathbb{P}(Y = 1, S = s)$ and the regression η .

Use the empirical distributions from \mathcal{D}_N .

With the unlabeled sample and $\hat{\eta}$ (trained on \mathcal{D}_n), define

$$\hat{\mathbb{E}}_{X|S=s}[f(X)] := \frac{1}{N_s} \sum_{i=n+1}^{n+N} f(X_i) \mathbf{1}\{S_i = s\}, \quad \hat{\mathbb{P}}_S(S = s) := \frac{N_s}{N}.$$

Then we estimate the (population) joint by

$$\boxed{\hat{\mathbb{P}}(Y = 1, S = s) := \hat{\mathbb{E}}_{X|S=s}[\hat{\eta}(X, s)] \hat{\mathbb{P}}_S(S = s)}$$

This equality holds by the law of total expectation and the definition of η :

$$\mathbb{P}(Y = 1 | S = s) = \mathbb{E}[Y | S = s] = \mathbb{E}[\mathbb{E}[Y | X, S = s] | S = s] = \mathbb{E}[\eta(X, s) | S = s].$$

Empirical Unfairness (Definition)

For any classifier g , an estimator $\hat{\eta}$ based on the labeled dataset \mathcal{D}_n , and an unlabeled sample \mathcal{D}_N , the **empirical unfairness** is defined as

$$\hat{\Delta}(g, \mathbb{P}) := \left| \frac{\hat{\mathbb{E}}_{X|S=1}[\hat{\eta}(X, 1) g(X, 1)]}{\hat{\mathbb{E}}_{X|S=1}[\hat{\eta}(X, 1)]} - \frac{\hat{\mathbb{E}}_{X|S=0}[\hat{\eta}(X, 0) g(X, 0)]}{\hat{\mathbb{E}}_{X|S=0}[\hat{\eta}(X, 0)]} \right|.$$

Here, $\hat{\mathbb{E}}_{X|S=s}[f(X)] = \frac{1}{N_s} \sum_{i=n+1}^{n+N} f(X_i) \mathbf{1}\{S_i = s\}$ and $\hat{\mathbb{P}}_S(S = s) = \frac{N_s}{N}$ are computed from the unlabeled dataset \mathcal{D}_N .

Key Remark: The empirical unfairness $\hat{\Delta}(g, \mathbb{P})$ is *data-driven* and does not involve any unknown population quantities.

Estimation of θ

Recall that the EO-optimal classifier g^* can be written in terms of a parameter θ^* . Since θ^* and the true distribution \mathbb{P} are unknown, we define the **empirical plug-in classifier** \hat{g}_θ by substituting empirical estimates:

$$\hat{g}_\theta(x, 1) = \mathbf{1}\left\{1 \leq \hat{\eta}(x, 1)\left(2 - \frac{\theta}{\hat{\mathbb{P}}(Y=1, S=1)}\right)\right\}, \quad \hat{g}_\theta(x, 0) = \mathbf{1}\left\{1 \leq \hat{\eta}(x, 0)\left(2 + \frac{\theta}{\hat{\mathbb{P}}(Y=1, S=0)}\right)\right\}.$$

We then estimate θ^* via

$$\hat{\theta} \in \arg \min_{\theta \in [-2, 2]} \hat{\Delta}(\hat{g}_\theta, \mathbb{P}).$$

Why $[-2, 2]$?

This interval ensures that the thresholds in \hat{g}_θ remain positive (i.e., well-defined), since $2 \pm \theta / \hat{\mathbb{P}}(Y = 1, S = s) > 0$ implies $|\theta| \leq 2$.

Theorem (Consistency of the plug-in rule). As $n, N \rightarrow \infty$ with $\hat{\eta}$ trained on \mathcal{D}_n independently of \mathcal{D}_N ,

$$\underbrace{\mathbb{E}[\Delta(\hat{g}, \mathbb{P})] \rightarrow 0}_{\text{asymptotically fair}} \quad \text{and} \quad \underbrace{\mathbb{E}[\mathcal{R}(\hat{g})] \rightarrow \mathcal{R}(g^*)}_{\text{asymptotically optimal}}.$$

► Assumptions

❶ Regression consistency (A1)

$$\mathbb{E}[|\hat{\eta}(X, S) - \eta(X, S)|] \rightarrow 0.$$

❷ No mass at thresholds / continuity (A2)

For $s \in \{0, 1\}$, the law of $\eta(X, s)$ has no point mass at the EO thresholds; small neighborhoods have vanishing probability.

❸ LLN on unlabeled sample (A3)

Empirical conditionals from \mathcal{D}_N converge: $\hat{\mathbb{E}}_{X|S=s}[f(X)] \rightarrow \mathbb{E}_{X|S=s}[f(X)]$ for bounded f .

❹ Shift identification (A4)

$\Theta = [-2, 2]$, and the population EO gap $\phi(\theta) := \text{TPR}_1(g_\theta) - \text{TPR}_0(g_\theta)$ has a unique root θ^* .

Consistency Proof Sketch (1/2)

Step 1. Population target. Let g_θ be the EO-threshold rule obtained by plugging the *true* quantities η and $\mathbb{P}(Y=1, S=s)$. Define the population EO gap

$$\phi(\theta) := \Delta(g_\theta, \mathbb{P}) = |\text{TPR}_1(g_\theta) - \text{TPR}_0(g_\theta)|.$$

By shift identification, ϕ has a unique root θ^* and $\phi(\theta^*) = 0$.

Step 2. Empirical objective. Define the data-driven gap

$$\hat{\phi}(\theta) := \hat{\Delta}(\hat{g}_\theta, \mathbb{P}),$$

where \hat{g}_θ uses $\hat{\eta}$ and $\hat{\mathbb{P}}(Y=1, S=s)$ (from \mathcal{D}_n and \mathcal{D}_N respectively).

Consistency Proof Sketch (2/3)

Step 3. Uniform convergence of the EO gap.

$$\sup_{\theta \in [-2, 2]} |\hat{\phi}(\theta) - \phi(\theta)| \xrightarrow{P} 0$$

Sketch. (i) Replace population conditionals by unlabeled empirical ones: LLN on \mathcal{D}_N (**A3**).

(ii) Replace η by $\hat{\eta}$: regression consistency in L^1 (**A1**).

(iii) Handle the indicator discontinuity: no mass at the moving thresholds (**A2**) makes the boundary band negligible.

Compact parameter set $\Theta = [-2, 2]$ (**A4**) gives uniformity.

Step 4. Argmin consistency for the shift. By the M-estimation argmin theorem on compact Θ , uniform convergence (Step 3) and uniqueness (A4) imply

$$\hat{\theta} \in \arg \min_{\theta \in [-2, 2]} \hat{\phi}(\theta) \implies \hat{\theta} \xrightarrow{P} \theta^*.$$

Consistency Proof Sketch (3/3)

Step 5. Conclude fairness and risk consistency. Decision regions differ only where $\eta(X, S)$ lies in a vanishing band around the thresholds or where $\hat{\theta}$ deviates from θ^* :

$$\mathbb{P}(\hat{g}_{\hat{\theta}}(X, S) \neq g_{\theta^*}(X, S)) \rightarrow 0.$$

Hence

$$\Delta(\hat{g}, \mathbb{P}) = \Delta(\hat{g}_{\hat{\theta}}, \mathbb{P}) \rightarrow \Delta(g_{\theta^*}, \mathbb{P}) = 0,$$

and for the risk,

$$|\mathcal{R}(\hat{g}_{\hat{\theta}}) - \mathcal{R}(g_{\theta^*})| \leq \mathbb{E}[|2\eta(X, S) - 1| \mathbf{1}\{\hat{g}_{\hat{\theta}} \neq g_{\theta^*}\}] \rightarrow 0.$$

Takeaway. Uniform control of the EO gap $\Rightarrow \hat{\theta} \rightarrow \theta^*$, and the plug-in classifier $\hat{g} = \hat{g}_{\hat{\theta}}$ becomes *asymptotically fair* and *risk-consistent*.

Conclusion

Contributions

We propose a label-efficient EO calibration method that leverages **unlabeled data** to learn a single group-dependent shift, avoiding retraining and heavy reliance on labels. Unlike prior approaches, we characterize the **EO-optimal rule in closed form** and establish strong **optimality and consistency guarantees**.

Experiment results

Across 5 datasets, our method consistently **reduces DEO with little or no loss in accuracy**. For example, with more unlabeled data (RF + Ours, fixed labeled budget $|\mathcal{D}_n| = 1/10$): COMPAS: ACC $0.68 \rightarrow 0.71$, DEO $0.07 \rightarrow 0.05$. Adult: ACC $0.79 \rightarrow 0.80$, DEO $0.06 \rightarrow 0.04$.