Verifiably Robust Conformal Prediction (NeurIPS 2024)

Sehyun Park February 25, 2025

Seoul National University - IDEA Lab.

1 Introduction

2 Preliminaries

3 Verifiably Robust Conformal Prediction (VRCP)

- 1) VRCP via Robust Inference
- 2) VRCP via Robust Calibration



Introduction

- Conformal Prediction provides prediction sets that guarantee a user-specified probability under the assumption that training and test data are exchangeable.
- Nevertheless, this guarantee is violated when the data is subjected to adversarial attacks.
- This paper proposes VRCP (Verifiably Robust Conformal Prediction), a new framework that leverages recent *neural network verification* methods to recover coverage guarantees under adversarial attacks.

Preliminaries

- $\boldsymbol{X} \subset \mathbb{R}^d$ and Y : a feature space and label space.
- $\mathcal{D} = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_m, y_m)\}$: i.i.d. sampled dataset.
- $\mathcal{D}_{train}, \mathcal{D}_{cal}$: a disjoint training and calibration sets where $\mathcal{D}_{train} \bigcup \mathcal{D}_{cal} = \mathcal{D}$ and $n = |\mathcal{D}_{cal}|$.
- f : a predictor fitted on \mathcal{D}_{train}
- $S_f: (\boldsymbol{X}, Y) \to \mathbb{R}$: a score function, such as
 - when f is a classifer $S_f(\boldsymbol{x}, y) = 1 f(\boldsymbol{x})_y$ where $f(\cdot)_y$ being y's predicted likelihood.
- $B_p(\boldsymbol{x},\epsilon)$: the ϵ -ball centered at $\boldsymbol{x} \in \mathbb{R}^d$ with respect to the p-norm $||\cdot||_p$.

- Intentionally adding imperceptible noise can degrade the performance of an AI model.
- This type of attack is called an "adversarial attack."



Figure 1: An example of an adversarial attack. From : Goodfellow, I. J. (2014). Explaining and harnessing adversarial examples

- Various approaches have been proposed to verify the robustness of NNs against adversarial attacks.
- The main target of these approaches is to find a verifier that computes a valid but not exact bound when a given neural network *f* is subjected to a perturbation within *ε*, such that :

$$f(\boldsymbol{x})_{y}^{\perp} \leq \inf_{\boldsymbol{x}' \in B_{p}(\boldsymbol{x},\epsilon)} \{f(\boldsymbol{x}')_{y}\}, \quad f(\boldsymbol{x})_{y}^{\top} \geq \sup_{\boldsymbol{x}' \in B_{p}(\boldsymbol{x},\epsilon)} \{f(\boldsymbol{x}')_{y}\}.$$
(1)

• This paper adopts and utilizes **CROWN**, the state-of-the-art (SotA) method in this field.

- Given a calibration set \mathcal{D}_{cal} , a test input \boldsymbol{x}_{test} , and a score function $S(\cdot, \cdot)$.
- Let $s_i = S(\boldsymbol{x}_i, y_i)$
- We construct the score distibution with calibration sets as :

$$F = \frac{\delta_{\infty}}{n+1} + \sum_{(\boldsymbol{x}_i, y_i) \in \mathcal{D}_{cal}} \frac{\delta_{s_i}}{n+1},$$
(2)

where δ_s is the Dirac distribution with parameter s, and δ_{∞} represents the unknown score (potentially infinite) of the test point.

- Given a miscoverage/error rate α and a test point (x_{test}, y_{test}) .
- Then, the prediction set $C(x_{test})$ is defined as:

$$C(x_{test}) = \{ y \in Y : S_f(x_{test}, y) \le Q_{1-\alpha}(F) \},$$
(3)

where $Q_{1-\alpha}(F)$ is the $1-\alpha$ quantile of F.

- *C*(*x*_{test}) satisfies the marginal coverage guarantee if the test point and the calibration points are exchangeable.
- However, when the data is subjected to adversarial attacks, this guarantee no longer holds.



Figure 2: With a target coverage of 0.9, targinal coverage and average set-size obtained by vanilla conformal predictiond, evaluated on the test set of CIFAR10. [1]

Verifiably Robust Conformal Prediction (VRCP)

- Given \mathcal{D}_{cal} , f, $S(\cdot, \cdot)$ and a test input \boldsymbol{x}_{test} .
- compute the prediction set for $oldsymbol{x}_{test}$ as follows.
 - 1. For each $y \in \mathcal{Y}$ we compute,

$$s^{\perp}(\boldsymbol{x}_{test}, y) = 1 - f(\boldsymbol{x}_{test})_{y}^{\top} \leq \inf_{\boldsymbol{x}' \in B(\boldsymbol{x}_{test}, \epsilon)} S(\boldsymbol{x}', y)$$
(4)

2. The robust prediction set is then defined as

$$C_{\epsilon}(\boldsymbol{x}_{test}) = \left\{ y : s^{\perp}(\boldsymbol{x}_{test}, y) \le Q_{1-\alpha}(F) \right\}$$
(5)

• Below, the authors show that we are able to maintain the marginal coverage guarantee for any ℓ_p -norm bounded adversarial attack.

Theorem 3.1

Let $\tilde{\boldsymbol{x}}_{test} = \boldsymbol{x}_{test} + \boldsymbol{\delta}$ for a clean test sample \boldsymbol{x}_{test} and $\|\boldsymbol{\delta}\|_p \leq \epsilon$. The prediction set $C_{\epsilon}(\tilde{\boldsymbol{x}}_{test})$ defined in Eq. (5) satisfies $\mathbb{P}[y_{test} \in C_{\epsilon}(\tilde{\boldsymbol{x}}_{test})] \geq 1 - \alpha$.

Proof :

$$\mathbb{P}\left[y_{test} \in C_{\epsilon}\left(\tilde{\boldsymbol{x}}_{test}\right)\right] = \mathbb{P}\left[s^{\perp}\left(\tilde{\boldsymbol{x}}_{test}, y_{test}\right) \leq Q_{1-\alpha}(F)\right]$$
$$\geq \mathbb{P}\left[\inf_{\boldsymbol{x}' \in B_{\epsilon}\left(\tilde{\boldsymbol{x}}_{test}\right)} S\left(\boldsymbol{x}', y_{test}\right) \leq Q_{1-\alpha}(F)\right] \text{ by Eq. (4)}$$
$$\geq \mathbb{P}\left[S\left(\boldsymbol{x}_{test}, y_{test}\right) \leq Q_{1-\alpha}(F)\right] \geq 1-\alpha. \quad \Box$$

- Given \mathcal{D}_{cal} , f, $S(\cdot, \cdot)$ and a test input \boldsymbol{x}_{test} .
- compute the prediction set for $oldsymbol{x}_{test}$ as follows.
 - 1. We compute the upper-bound score distribution with calibration sets as:

$$F^{\top} = \frac{\delta_{\infty}}{(n+1)} + \sum_{(\boldsymbol{x}_i, y_i) \in \mathcal{D}_{cal}} \frac{\delta_{s_i^{\top}}}{n+1}, \text{ where } s_i^{\top} \ge \sup_{\boldsymbol{x}' \in B_p(\boldsymbol{x}_i, \epsilon)} S\left(\boldsymbol{x}', y_i\right) \quad (6)$$

2. The robust prediction set is then defined as

$$C_{\epsilon}\left(\boldsymbol{x}_{test}\right) = \left\{ y : S\left(\boldsymbol{x}_{test}, y\right) \le Q_{1-\alpha}\left(\boldsymbol{F}^{\top}\right) \right\}$$
(7)

Theorem 3.2

Let $\tilde{\boldsymbol{x}}_{test} = \boldsymbol{x}_{test} + \boldsymbol{\delta}$ for a clean test sample \boldsymbol{x}_{test} and $\|\boldsymbol{\delta}\|_p \leq \epsilon$. The prediction set $C_{\epsilon}(\tilde{\boldsymbol{x}}_{test})$ defined in Eq. (7) satisfies $\mathbb{P}[y_{test} \in C_{\epsilon}(\tilde{\boldsymbol{x}}_{test})] \geq 1 - \alpha$.

Proof :

$$\mathbb{P}\left[y_{test} \in C_{\epsilon}\left(\tilde{\boldsymbol{x}}_{test}\right)\right] = \mathbb{P}\left[S\left(\tilde{\boldsymbol{x}}_{test}, y_{test}\right) \leq Q_{1-\alpha}\left(F^{\top}\right)\right]$$

$$\geq \mathbb{P}\left[S\left(\tilde{\boldsymbol{x}}_{test}, y_{test}\right) \leq Q_{1-\alpha}\left(\left\{\sup_{\boldsymbol{x}' \in B_{\epsilon}\left(\boldsymbol{x}_{i}\right)}S\left(\boldsymbol{x}', y_{i}\right)\right\}_{\left(\boldsymbol{x}_{i}, y_{i}\right) \in \mathcal{D}_{cal}} \cup \{\infty\}\right)\right]$$

$$\geq \mathbb{P}\left[\sup_{\boldsymbol{x}' \in B_{\epsilon}\left(\boldsymbol{x}_{test}\right)}S\left(\boldsymbol{x}', y_{test}\right) \leq Q_{1-\alpha}\left(\left\{\sup_{\boldsymbol{x}' \in B_{\epsilon}\left(\boldsymbol{x}_{i}\right)}S\left(\boldsymbol{x}', y_{i}\right)\right\}_{\left(\boldsymbol{x}_{i}, y_{i}\right) \in \mathcal{D}_{cal}} \cup \{\infty\}\right)\right]$$

$$\geq 1-\alpha. \quad \Box$$

Experiments

- Dataset : CIFAR10, CIFAR100, TinyImageNet
- Models : CNN model
- Attacks : PGD attack. ℓ_2 -norm bounded attacks with $\epsilon = 0.02$ or $\epsilon = 0.03$.
- Target coverage : $1 \alpha = 0.9$, repeated 50 times.

Results

	CIFAR10		CIFAR100		TinyImageNet	
Method	Coverage	Size	Coverage	Size	Coverage	Size
Vanilla	0.878 ± 0.002	1.721±0.008	0.890 ± 0.002	6.702±0.058	0.886 ± 0.002	38.200±0.252
RSCP+ RSCP+ (PTT)	1.000±0.000 0.983±0.008	10.000±0.000 8.357±0.780	1.000±0.000 0.925±0.010	100.000±0.000 26.375±9.675	1.000±0.000 0.931±0.013	200.000±0.000 90.644±20.063
VRCP–I VRCP–C	0.986±0.000 0.995±0.000	4.451±0.011 5.021±0.010	0.971±0.001 0.983±0.000	22.530±0.107 23.676±0.131	0.958±0.001 0.965±0.001	72.486±0.311 77.761±0.352

End