# Statistical Learning Theory

3. Vapnik-Chervonenkis (VC) theory

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#### Definition (Bounded Differences Condition)

Let  $g : \mathcal{X} \to \mathbb{R}$  and constants  $c_i$  be given. Then g is said to satisfy the bounded differences condition (with constants  $c_i$ ) if

$$\sup_{x_1,\ldots,x_n,x_i'} \left| g\left(x_1,\ldots,x_n\right) - g\left(x_1,\ldots,x_i',\ldots,x_n\right) \right| \le c_i$$

for every *i*.

# **Theorem (Bounded Differences Inequality)** Suppose that $X_1, \ldots, X_n$ are indepent random variables. If $g : \mathcal{X} \to \mathbb{R}$ satisfies the bounded differences condition, then

$$\mathbb{P}\left[\mid g\left(X_1,\ldots,X_n\right) - \mathbb{E}\left[g\left(X_1,\ldots,X_n\right)\mid > t\right] \le 2\exp\left(-\frac{2t^2}{\sum_i c_i^2}\right)\right]$$

- The upper bounds proved so far are meaningful only for a finite dictionary *H*, because if *M* = |*H*| is infinite all of the bounds we have will simply be infinity.
- To extend previous results to the infinite case, we essentially need the condition that only a finite number of elements in an infinite dictionary  $\mathcal{H}$  really matter.
- This is the objective of the VapnikChervonenkis (VC) theory which was developed in 1971 .

# **Empirical measure**

• Recall that the key quantity we need to control is

$$2\sup_{h\in\mathcal{H}}\left(\hat{R}_n(h)-R(h)\right).$$

- Instead of the union bound which would not work in the infinite case, we seek some bound that potentially depends on *n* and the complexity of the set *H*.
- One approach is to consider some metric structure on  $\mathcal{H}$  and hope that if two elements in  $\mathcal{H}$  are close, then the quantity evaluated at these two elements are also close.
- On the other hand, the VC theory is more combinatorial and does not involve any metric space structure as we will see.

# • By definition

$$\hat{R}_n(h) - R(h) = \frac{1}{n} \sum_{i=1}^n \left( \mathbb{I}(h(X_i) \neq Y_i) - \mathbb{E}\left[ \mathbb{I}(h(X_i) \neq Y_i) \right] \right)$$

- Let Z = (X, Y) and Z<sub>i</sub> = (X<sub>i</sub>, Y<sub>i</sub>), and let A denote the class of measurable sets in the sample space X × {0, 1}.
- For a classifier *h*, define  $A_h \in \mathcal{A}$  by

$$\{Z_i \in A_h\} = \{h(X_i) \neq Y_i\}$$

• Moreover, define measures  $\mu_n$  and  $\mu$  on  $\mathcal{A}$  by

$$\mu_n(A) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}(Z_i \in A) \text{ and } \mu(A) = \mathbb{P}[Z_i \in A]$$

for  $A \in \mathcal{A}$ .

• With this notation, we have proved that

$$\sup_{h\in\mathcal{H}}\hat{R}_n(h)-R(h)=\sup_{A\in\mathcal{A}}|\mu_n(A)-\mu(A)|\leq \sqrt{\frac{\log(2|\mathcal{A}|/\delta)}{2n}}$$

# **Empirical measure**

- Since this is not accessible in the infinite case, we will derive an upper bound by use of bounded differences inequality.
- If we change the value of only one  $z_i$  in the function

$$z_1,\ldots,z_n\mapsto \sup_{A\in A}|\mu_n(A)-\mu(A)|,$$

the value of the function will differ by at most 1/n.

- Hence it satisfies the bounded difference assumption with  $c_i = 1/n$  for all  $1 \le i \le n$ .
- Applying the bounded difference inequality, we get that

$$\left|\sup_{A \in \mathcal{A}} |\mu_n(A) - \mu(A)| - \mathbb{E}[\sup_{A \in \mathcal{A}} |\mu_n(A) - \mu(A)|]\right| \le \sqrt{\frac{\log(2/\delta)}{2n}}.$$
  
with probability at least  $1 - \delta$ .

- We will drive an upper bound of E[sup<sub>A∈A</sub> |µ<sub>n</sub>(A) − µ(A)|], and symmetrization is a frequently used technique for this purpose.
- Let  $\mathcal{D} = \{Z_1, \ldots, Z_n\}$  be the sample set.
- To employ symmetrization, we take another independent copy of the sample set  $\mathcal{D}' = \{Z'_1, \dots, Z'_n\}$ .
- This sample only exists for the proof, so it is sometimes referred to as a ghost sample.

• Then we have

$$\mu(A) = \mathbb{P}[Z \in A]$$
$$= \mathbb{E}\left[\frac{1}{n}\sum_{i=1}^{n}\mathbb{I}\left(Z'_{i} \in A\right)\right]$$
$$= \mathbb{E}\left[\frac{1}{n}\sum_{i=1}^{n}\mathbb{I}\left(Z'_{i} \in A\right) \mid \mathcal{D}\right]$$
$$= \mathbb{E}\left[\mu'_{n}(A) \mid \mathcal{D}\right]$$

where  $\mu'_n := \frac{1}{n} \sum_{i=1}^n \mathbb{I}(Z'_i \in A)$ .

Thus by Jensen's inequality,

$$\mathbb{E}\left[\sup_{A\in\mathcal{A}}|\mu_{n}(A)-\mu(A)|\right] = \mathbb{E}\left[\sup_{A\in\mathcal{A}}|\mu_{n}(A)-\mathbb{E}\left[\mu_{n}'(A)\mid\mathcal{D}\right]|\right]$$
$$\leq \mathbb{E}\left[\sup_{A\in\mathcal{A}}\mathbb{E}\left[|\mu_{n}(A)-\mu_{n}'(A)|\mid\mathcal{D}\right]\right]$$
$$\leq \mathbb{E}\left[\sup_{A\in\mathcal{A}}|\mu_{n}(A)-\mu_{n}'(A)|\right]$$
$$= \mathbb{E}\left[\sup_{A\in\mathcal{A}}\left|\frac{1}{n}\sum_{i=1}^{n}\left(\mathbb{I}\left(Z_{i}\in\mathcal{A}\right)-\mathbb{I}\left(Z_{i}'\in\mathcal{A}\right)\right)\right|\right]$$

.

• Since  $\mathcal{D}'$  has the same distribution of  $\mathcal{D}$ , by symmetry  $\mathbb{I}(Z_i \in A) - \mathbb{I}(Z'_i \in A)$  has the same distribution as  $\sigma_i(\mathbb{I}(Z_i \in A) - \mathbb{I}(Z'_i \in A))$  where  $\sigma_1, \ldots, \sigma_n$  are i.i.d. Rad  $(\frac{1}{2})$ , i.e.

$$\mathbb{P}\left[\sigma_{i}=1\right]=\mathbb{P}\left[\sigma_{i}=-1\right]=\frac{1}{2}$$

and  $\sigma_i$  's are taken to be independent of both samples.

• Therefore,

$$\mathbb{E}[\sup_{A \in \mathcal{A}} | \mu_n(A) - \mu(A)|] \\ \leq \mathbb{E}\left[\sup_{A \in \mathcal{A}} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i \left( \mathbb{I}(Z_i \in A) - \mathbb{I}(Z'_i \in A) \right) \right| \right] \\ \leq 2\mathbb{E}\left[\sup_{A \in \mathcal{A}} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i \mathbb{I}(Z_i \in A) \right| \right] \cdots (*)$$

- Using symmetrization we have bounded  $\mathbb{E}\left[\sup_{A \in A} |\mu_n(A) - \mu(A)|\right]$ . by a much nicer quantity.
- Yet we still need an upper bound of the last quantity that depends only on the structure of A but not on the random sample {Z<sub>i</sub>}.
- This is achieved by taking the supremum over all  $z_i \in \mathcal{X} \times \{0, 1\} =: \mathcal{Y}.$

## Definition

The Rademacher complexity of a family of sets  ${\cal A}$  in a space  ${\cal Y}$  is defined to be the quantity

$$\mathcal{R}_n(\mathcal{A}) = \sup_{z_1, \dots, \bar{z}_n \in \mathcal{Y}} \mathbb{E} \left[ \sup_{A \in \mathcal{A}} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i \mathbb{I} \left( z_i \in A \right) \right| \right]$$

The Rademacher complexity of a set  $B \subset \mathbb{R}^n$  is defined to be

$$\mathcal{R}_n(B) = \mathbb{E}\left[\sup_{b\in B}\left|\frac{1}{n}\sum_{i=1}^n\sigma_i b_i\right|\right]$$

 $\bullet\,$  We conclude from (\*) and the definition that

$$\mathbb{E}[\sup_{A\in\mathcal{A}}|\mu_n(A)-\mu(A)|]\leq 2\mathcal{R}_n(\mathcal{A}).$$

- In the definition of Rademacher complexity of a set, the quantity |<sup>1</sup>/<sub>n</sub> ∑<sup>n</sup><sub>i=1</sub> σ<sub>i</sub>b<sub>i</sub>| measures how well a vector b ∈ B correlates with a random sign pattern {σ<sub>i</sub>}.
- The more complex *B* is, the better some vector in *B* can replicate a sign pattern.
- In particular, if B is the full hypercube  $[-1, 1]^n$ , then  $\mathcal{R}_n(B) = 1$ .
- However, if  $B \subset [-1,1]^n$  contains only k -sparse vectors, then  $\mathcal{R}_n(B) = k/n$ .
- Hence  $\mathcal{R}_n(B)$  is indeed a measurement of the complexity of the set *B*.

• The set of vectors to our interest in the definition of Rademacher complexity of  $\mathcal{A}$  is

$$T(z) := \left\{ \left( \mathbb{I}\left(z_1 \in A\right), \dots, \mathbb{I}\left(z_n \in A\right) \right)^T, A \in \mathcal{A} \right\}.$$

- Thus the key quantity here is the cardinality of T(z), i.e., the number of sign patterns these vectors can replicate as A ranges over A.
- Although the cardinality of A may be infinite, the cardinality of T(z) is bounded by 2<sup>n</sup>.

- We will complete the analysis of the performance of the empirical risk minimizer under a constraint on the VC dimension of the family of classifiers.
- To that end, we will see how to control Rademacher complexities using shatter coefficients.
- Moreover, we will see how the problem of controlling uniform deviations of the empirical measure μ<sub>n</sub> from the true measure μ as done by Vapnik and Chervonenkis relates to our original classification problem.

# Shattering

• Recall from the previous slide that we are interested in sets of the form

 $T(z) := \left\{ \left( \mathbb{I}\left(z_1 \in A\right), \dots, \mathbb{I}\left(z_n \in A\right)\right), A \in \mathcal{A} \right\}, z = (z_1, \dots, z_n) \cdots (**)$ 

- In particular, the cardinality of T(z), i.e., the number of binary patterns these vectors can replicate as A ranges over A, will be of critical importance, as it will arise when controlling the Rademacher complexity.
- Although the cardinality of A may be infinite, the cardinality of T(z) is always at most 2<sup>n</sup>.
- When it is of the size  $2^n$ , we say that  $\mathcal{A}$  shatters the set  $z_1, \ldots, z_n$ . Formally, we have the following definition.

**Definition** A collection of sets A shatters the set of points  $\{z_1, z_2, \ldots, z_n\}$ 

$$\operatorname{\mathsf{card}}\left\{\left(\mathbb{I}\left(z_{1}\in A
ight),\ldots,\mathbb{I}\left(z_{n}\in A
ight)
ight),A\in\mathcal{A}
ight\}=2^{n}$$

- The sets of points {z<sub>1</sub>, z<sub>2</sub>,..., z<sub>n</sub>} that we are interested are realizations of the pairs Z<sub>1</sub> = (X<sub>1</sub>, Y<sub>1</sub>),..., Z<sub>n</sub> = (X<sub>n</sub>, Y<sub>n</sub>) and may, in principle take any value over the sample space.
- Therefore, we define the shatter coefficient to be the largest cardinality that we may obtain.

#### Definition

The shatter coefficients of a class of sets A is the sequence of numbers  $\{S_A(n)\}_{n\geq 1}$ , where for any  $n\geq 1$ 

$$\mathcal{S}_{\mathcal{A}}(n) = \sup_{z_1,...,z_n} \operatorname{card} \left\{ \left( \mathbb{I}\left(z_1 \in A\right), \ldots, \mathbb{I}\left(z_n \in A\right) \right), A \in \mathcal{A} \right\}$$

and the suprema are taken over the whole sample space.

- By definition, the n th shatter coefficient S<sub>A</sub>(n) is equal to 2<sup>n</sup> if there exists a set {z<sub>1</sub>, z<sub>2</sub>,..., z<sub>n</sub>} that A shatters.
- The largest of such sets is precisely the Vapnik-Chervonenkis or VC dimension.

#### Definition

The Vapnik-Chervonenkis dimension, or VC -dimension of  $\mathcal{A}$  is the largest integer d such that  $\mathcal{S}_{\mathcal{A}}(d) = 2^d$ . We write  $VC(\mathcal{A}) = d$ . If  $\mathcal{S}_{\mathcal{A}}(n) = 2^n$  for all positive integers n, then  $VC(\mathcal{A}) := \infty$ 

- In other words, A shatters some set of points of cardinality d but shatters no set of points of cardinality d + 1.
- In particular, A also shatters no set of points of cardinality  $d' \ge d$  so that the VC dimension is well defined.
- In the sequel, we will see that the VC dimension will play the role similar to of cardinality, but on an exponential scale.
- For interesting classes A such that  $card(A) = \infty$ , we also may have  $VC(A) < \infty$ .

- For example, assume that A is the class of half-lines,
   A = {(-∞, a], a ∈ ℝ} ∪ {[a, ∞), a ∈ ℝ}, which is clearly infinite.
- Then, we can clearly shatter a set of size 2 but we for three points z<sub>1</sub>, z<sub>2</sub>, z<sub>3</sub>, ∈ ℝ, if for example z<sub>1</sub> < z<sub>2</sub> < z<sub>3</sub>, we cannot create the pattern (0, 1, 0) (see Figure 1 in the next slide).
- Indeed, half lines can can only create patterns with zeros followed by ones or with ones followed by zeros but not an alternating pattern like (0, 1, 0).

# Shattering

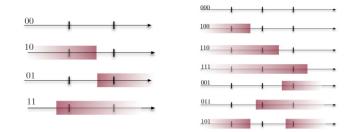


Figure 1 : If  $\mathcal{A} = \{$  halflines  $\}$ , then any set of size n = 2 is shattered because we can create all  $2^n = 40/1$  patterns (left); if n = 3 the pattern (0, 1, 0) cannot be reconstructed:  $\mathcal{S}_{\mathcal{A}}(3) = 7 < 2^3$  (right). Therefore, VC( $\mathcal{A}$ ) = 2

# The VC inequality

• We have now introduced all the ingredients necessary to state the main result of this section: the VC inequality.

**Theorem (VC inequality)** For any family of sets A with VC dimension VC(A) = d, it holds

$$\mathbb{E} \sup_{A \in \mathcal{A}} |\mu_n(A) - \mu(A)| \le 2\sqrt{\frac{2d \log(2en/d)}{n}}$$

- Note that this result holds even if A is infinite as long as its VC dimension is finite.
- Moreover, observe that log(|A|) has been replaced by a term of order d log(2en/d).
- To prove the VC inequality, we proceed in three steps:

# The VC inequality

1. Symmetrization, to bound the quantity of interest by the Rademacher complexity:

$$\mathbb{E}[\sup_{A\in\mathcal{A}} | \mu_n(A) - \mu(A)|] \leq 2\mathcal{R}_n(\mathcal{A}).$$

We have already done this step in the previous lecture.

2. Control of the Rademacher complexity using shatter coefficients. We are going to show that

$$\mathcal{R}_n(\mathcal{A}) \leq \sqrt{\frac{2\log\left(2\mathcal{S}_{\mathcal{A}}(n)
ight)}{n}}$$

3. We are going to need the Sauer-Shelah lemma to bound the shatter coefficients by the VC dimension. It will yield

$$\mathcal{S}_{\mathcal{A}}(n) \leq \left(\frac{en}{d}\right)^d, \quad d = \mathsf{VC}(\mathcal{A})$$

Put together, these three steps yield the VC inequality.

• We need the following Lemma whose proof is HW.

**Lemma** For any  $B \subset \mathbb{R}^n$ , such that  $|B| < \infty$ :, it holds

$$\mathcal{R}_n(B) = \mathbb{E}\left[\max_{b \in B} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i b_i \right| \right] \le \max_{b \in B} |b|_2 \frac{\sqrt{2\log(2|B|)}}{n}$$

where  $|\cdot|_2$  denotes the Euclidean norm.

# STEP 2: CONTROL OF THE RADEMACHER COMPLEX-ITY

• We apply the above Lemma to our problem by observing that

$$\mathcal{R}_n(\mathcal{A}) = \sup_{z_1,\ldots,z_n} \mathcal{R}_n(T(z)).$$

- In particular, since  $T(z) \subset \{0,1\}^n$ , we have  $|b|_2 \leq \sqrt{n}$  for all  $b \in T(z)$ .
- Moreover, by definition of the shatter coefficients,  $|T(z)| \leq S_A(n).$
- Together with the above lemma, it yields the desired inequality:

$$\mathcal{R}_n(\mathcal{A}) \leq \sqrt{\frac{2\log(2S_{\mathcal{A}}(n))}{n}}.$$

# STEP 3: SAUER-SHELAH LEMMA

- We need to use a lemma from combinatorics to relate the shatter coefficients to the VC dimension.
- A priori, it is not clear from its definition that the VC dimension may be at all useful to get better bounds.
- Recall that steps 1 and 2 put together yield the following bound

$$\mathbb{E}[\sup_{A \in A} \mid \mu_n(A) - \mu(A) \mid] \le 2\sqrt{\frac{2\log\left(2\mathcal{S}_{\mathcal{A}}(n)\right)}{n}} \cdots (* * *)$$

 In particular, if S<sub>A</sub>(n) is exponential in n, the bound (\*\*\*) is not informative, i.e., it does not imply that the uniform deviations go to zero as the sample size n goes to infinity.

- The VC inequality suggest that this is not the case as soon as  $VC(A) < \infty$  but it is not clear a priori.
- Indeed, it may be the case that  $S_A(n) = 2^n$  for  $n \le d$  and  $S_A(n) = 2^n 1$  for n > d, which would imply that  $VC(A) = d < \infty$  but that the right-hand side in (\*\*\*) is larger than 2 for all n.
- It turns our that this can never be the case: if the VC dimension is finite, then the shatter coefficients are at most polynomial in *n*, which is stated in the Sauer-Shelah lemma.

**Lemma (Sauer-Shelah)**  
If 
$$VC(A) = d$$
, then  $\forall n \ge 1$ ,

$$\mathcal{S}_{\mathcal{A}}(n) \leq \sum_{k=0}^{d} \left( \begin{array}{c} n \\ k \end{array} \right) \leq \left( rac{en}{d} \right)^{d}$$

To sum up everything, we have the following corollary.

**Corollary (VC inequality)** For any family of sets A such that VC(A) = d and any  $\delta \in (0, 1)$ , it holds with probability at least  $1 - \delta$ ,

$$\sup_{A \in \mathcal{A}} |\mu_n(A) - \mu(A)| \le 2\sqrt{\frac{2d\log(2en/d)}{n}} + \sqrt{\frac{\log(2/\delta)}{2n}}$$

# Application to ERM

- The VC inequality provides an upper bound for sup<sub>A∈A</sub> |μ<sub>n</sub>(A) – μ(A)| in terms of the VC dimension of the class of sets A.
- This result translates directly to our quantity of interest:

$$\sup_{h \in \mathcal{H}} \left| \hat{R}_n(h) - R(h) \right| \le 2\sqrt{\frac{2\operatorname{VC}(\mathcal{A})\log\left(\frac{2en}{\operatorname{VC}(\mathcal{A})}\right)}{n}} + \sqrt{\frac{\log(2/\delta)}{2n}}$$

where  $\mathcal{A} = \{A_h : h \in \mathcal{H}\}$  and

 $A_h = \{(x, y) \in \mathcal{X} \times \{0, 1\} : h(x) \neq y\}.$ 

- Unfortunately, the VC dimension of this class of subsets of  $\mathcal{X}\times\{0,1\} \text{ is not very natural}.$
- Since, a classifier *h* is a {0,1} valued function, it is more natural to consider the VC dimension of the family

$$\overline{\mathcal{A}} = \{\{h = 1\} : h \in \mathcal{H}\} = \{A : \exists h \in \mathcal{H}, h(\cdot) = \mathbb{I}(\cdot \in A)\}.$$

# **Definition** We define the VC dimension VC( $\mathcal{H}$ ) of $\mathcal{H}$ to be the VC dimension of $\overline{\mathcal{A}}$ .

- It is not clear how  $VC(\overline{A})$  relates to the quantity VC(A).
- Fortunately, these two are actually equal as indicated in the following lemma.

#### Lemma

Define the two families for sets:  $\mathcal{A} = \{A_h : h \in \mathcal{H}\} \in 2^{\mathcal{X} \times \{0,1\}}$ where  $A_h = \{(x, y) \in \mathcal{X} \times \{0,1\} : h(x) \neq y\}$  and  $\overline{A} = \{\{h = 1\} : h \in \mathcal{H}\} \in 2^{\mathcal{X}}$  Then,  $\mathcal{S}_{\mathcal{A}}(n) = \mathcal{S}_{\overline{\mathcal{A}}}(n)$  for all  $n \ge 1$ . It implies  $VC(\mathcal{A}) = VC(\overline{\mathcal{A}})$ . It yields the following corollary to the VC inequality.

**Corollary** Let  $\mathcal{H}$  be a family of classifiers with VC dimension d. Then the empirical risk classifier  $\hat{h}^{erm}$  over  $\mathcal{H}$  satisfies

$$R\left(\hat{h}^{\mathrm{erm}}
ight) \leq \min_{h\in\mathcal{H}} R(h) + 4\sqrt{\frac{2d\log(2en/d)}{n}} + \sqrt{\frac{\log(2/\delta)}{2n}}$$

with probability  $1 - \delta$ .