Statistical Learning Theory

2. Statistical learning theory for binary classification

- In the previous section, we looked broadly at the problems that machine learning seeks to solve and the techniques we will cover in this course.
- Today, we will focus on one such problem, binary classification, and review some important notions that will be foundational for the rest of the course.

- Recall the setup of binary classification: we observe a sequence (X₁, Y₁),..., (X_n, Y_n) of n independent draws from a joint distribution P_{X,Y}.
- The variable Y (called the label) takes values in {0,1}, and the variable X takes values in some space X representing "features" of the problem.

Bayes Classifier

- Since Y is supported on {0,1}, the conditional random variable Y | X is distributed according to a Bernoulli distribution.
- We write $Y \mid X \sim \text{Bernoulli}(\eta(X))$, where

$$\eta(X) = \mathbb{P}(Y = 1 \mid X) = \mathbb{E}[Y \mid X]$$

(The function η is called the regression function.)

- We begin by defining an optimal classifier called the Bayes classifier. Intuitively, the Bayes classifier is the classifier that "knows" η -it is the classifier we would use if we had perfect access to the distribution Y | X.
- (*) It will turn out that the Bayes classifier does not depend on the marginal distribution P_X of X. This is why we can focus on discriminative approaches without loss of generality.

Definition

The Bayes classifier of X given Y, denoted h^* , is the function defined by the rule

$$h^*(x) = \left\{ egin{array}{cc} 1 & ext{if } \eta(x) > 1/2 \ 0 & ext{if } \eta(x) \leq 1/2. \end{array}
ight.$$

In other words, $h^*(X) = 1$ whenever $\mathbb{P}(Y = 1 \mid X) > \mathbb{P}(Y = 0 \mid X).$

- Our measure of performance for any classifier h (that is, any function mapping X to {0,1}) will be the classification error:
 R(h) = ℙ(Y ≠ h(X)).
- The Bayes risk is the value $R^* = R(h^*)$ of the classification error associated with the Bayes classifier.
- The following theorem establishes that the Bayes classifier is optimal with respect to this metric.

Theorem

For any classifier h, the following identity holds:

$$R(h) - R(h^*) = \int_{h \neq h^*} |2\eta(x) - 1| P_x(dx)$$

= $\mathbb{E}_X [|2\eta(X) - 1| 1(h(X) \neq h^*(X))]$ (1)

where $h = h^*$ is the (measurable) set $\{x \in \mathcal{X} \mid h(x) \neq h^*(x)\}$. In particular, since the integrand is nonnegative, the classification error R^* of the Bayes classifier is the minimizer of R(h) over all classifiers h. Moreover,

$$\mathsf{R}\left(h^{*}
ight)=\mathbb{E}[\min(\eta(X),1-\eta(X))]\leqrac{1}{2}$$

Remark 1

- The quantity R(h) R(h*) in the statement of the theorem above is called the excess risk of h and denoted E(h).
 ("Excess," that is, above the Bayes classifier.)
- The theorem implies that $\mathcal{E}(h) \geq 0$.

Remark 2

- The risk of the Bayes classifier R^* equals 1/2 if and only if $\eta(X) = 1/2$ almost surely.
- This maximal risk for the Bayes classifier occurs precisely when Y "contains no information" about the feature variable X.
- Equation (1) makes clear that the excess risk weighs the discrepancy between h and h* according to how far η is from 1/2.
- When η is close to 1/2, no classifier can perform well and the excess risk is low.
- When η is far from 1/2, the Bayes classifier performs well and we penalize classifiers that fail to do so more heavily.

Bayes Classifier

- Linear discriminant analysis attacks binary classification by putting some model on the data (i.e. generative model).
- One way to achieve this is to impose some distributional assumptions on the conditional distributions X | Y = 0 and X | Y = 1.
- We can reformulate the Bayes classifier in these terms by applying Bayes' rule:

$$\eta(x) = \mathbb{P}(Y = 1 \mid X = x)$$

=
$$\frac{\mathbb{P}(X = x \mid Y = 1)\mathbb{P}(Y = 1)}{\mathbb{P}(X = x \mid Y = 1)\mathbb{P}(Y = 1) + \mathbb{P}(X = x \mid Y = 0)\mathbb{P}(Y = 0)}$$

(In general, when P_X is a continuous distribution, we should consider infinitesimal probabilities $\mathbb{P}(X \in dx)$.)

- Assume that X | Y = 0 and X | Y = 1 have densities p_0 and p_1 .
- Also let P(Y = 1) = π is some constant reflecting the underlying tendency of the label Y. (Typically, we imagine that π is close to 1/2, but that need not be the case: in many applications, such as anomaly detection, Y = 1 is a rare event.)
- Then $h^*(X) = 1$ whenever $\eta(X) \ge 1/2$, or, equivalently, whenever

$$\frac{p_1(x)}{p_0(x)} \ge \frac{1-\pi}{\pi}$$

- When π = 1/2, this rule amounts to reporting 1 or 0 by comparing the densities p₁ and p₀.
- For instance, in Figure 2, if π = 1/2 then the Bayes classifier reports 1 whenever p₁ ≥ p₀, i.e., to the right of the dotted line, and 0 otherwise.
- On the other hand, when π is far from 1/2, the Bayes classifier is weighed towards the underlying bias of the label variable Y.

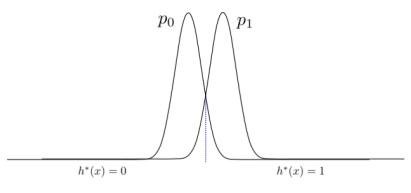


Figure 1: The Bayes classifier when $\pi = 1/2$

- The above considerations are all probabilistic, in the sense that they discuss properties of some underlying probability distribution.
- The statistician does not have access to the true probability distribution P_{X,Y}; she only has access to i.i.d. samples (X₁, Y₁),..., (X_n, Y_n).
- We consider now this statistical perspective.
- However, note that the underlying distribution $P_{X,Y}$ still appears explicitly in what follows, since that is how we measure our performance: we judge the classifiers we produced on future i.i.d. draws from $P_{X,Y}$.

Empirical Risk Minimization

- Given data D_n = {(X₁, Y₁),..., (X_n, Y_n)}, we build a classifier ĥ_n(X), which is random in two senses: it is a function of a random variable X and also depends implicitly on the random data D_n.
- As above, we judge a classifier according to the quantity $\mathcal{E}(\hat{h}_n)$. This is a random variable: though we have integrated out X, the excess risk still depends on the data \mathcal{D}_n .
- We therefore will consider bounds both on its expected value and bounds that hold in high probability.
- In any case, the bound $\mathcal{E}\left(\hat{h}_{n}
 ight)\geq 0$ always holds.

Definition The empirical risk of a classifier h is given by

$$\hat{R}_n(h) = \frac{1}{n} \sum_{i=1}^n \mathbf{1} \left(Y_i \neq h(X_i) \right)$$

- Minimizing the empirical risk over the family of all classifiers is useless, since we can always minimize the empirical risk by mimicking the data and classifying arbitrarily otherwise.
- We therefore limit our attention to classifiers in a certain family \mathcal{H} .

Definition

The Empirical Risk Minimizer (*ERM*) over \mathcal{H} is any element \hat{h}^{erm} of the set $\operatorname{argmin}_{h\in\mathcal{H}}\hat{R}_n(h)$.

- (*) In fact, even an approximate solution will do: our bounds will still hold whenever we produce a classifier \hat{h} satisfying $\hat{R}_n(\hat{h}) \leq \inf_{h \in \mathcal{H}} R_n(h) + \varepsilon$.
- (*) ERM is one of many learning algorithms. We focus on ERM since there are well developed learning theories.

- In order for our results to be meaningful, the class \mathcal{H} must be much smaller than the space of all classifiers.
- On the other hand, we also hope that the risk of \hat{h}^{erm} will be close to the Bayes risk, but that is unlikely if \mathcal{H} is too small.
- We will learn how to quantify this tradeoff.

Oracle Inequalities

- An oracle is a mythical classifier, one that is impossible to construct from data alone but whose performance we nevertheless hope to mimic.
- Specifically, given *H* we define *h* to be an element of argmin_{h∈H} *R*(*h*) a classifier in *H* that minimizes the true risk.
- Of course, we cannot determine \bar{h} , but we can hope to prove a bound of the form

$$R(\hat{h}) \le R(\bar{h}) + \text{ something small.}$$
 (2)

Since h
 is the best minimizer in H
 given perfect knowledge of
 the distribution, a bound of the form given in Equation(2)
 would imply that h
 has performance that is almost best-inclass.

- There is a natural tradeoff between the two terms on the right-hand side of Equation (??).
- When H is small, we expect the performance of the oracle h
 to suffer, but we may hope to approximate h
 quite closely.
- (*) Indeed, at the limit where *H* is a single function, the "something small" in Equation (2) is equal to zero.

Oracle Inequalities

- On the other hand, as \mathcal{H} grows the oracle will become more powerful but approximating it becomes more statistically difficult.
- In other words, we need a larger sample size to achieve the same measure of performance.
- Since $R(\hat{h})$ is a random variable, we ultimately want to prove a bound in expectation or tail bound of the form

$$\mathbb{P}\left({R}(\hat{h}) \leq R(ar{h}) + \Delta_{n,\delta}(\mathcal{H})
ight) \geq 1 - \delta$$

where $\Delta_{n,\delta}(\mathcal{H})$ is some explicit term depending on our sample size and our desired level of confidence.

• In the end, we should recall that

$$\mathcal{E}(\hat{h}) = R(\hat{h}) - R(h^*) = (R(\hat{h}) - R(\bar{h})) + (R(\bar{h}) - R(h^*)).$$

- The second term in the above equation is the approximation error, which is unavoidable once we fix the class \mathcal{H} .
- Oracle inequalities give a means of bounding the first term, the stochastic error.

Theorem (Hoeffding's Theorem) Let $X_1, ..., X_n$ be n independent random variables such that $X_i \in [0, 1]$ almost surely. Then for any t > 0,

$$\mathbb{P}\left(\left|\frac{1}{n}\sum_{i=1}^{n}X_{i}-\mathbb{E}X_{i}\right|>t\right)\leq 2e^{-2nt^{2}}$$

• In other words, deviations from the mean decay exponentially fast in *n* and *t*.

Maximal inequality

• Hoeffding's Theorem implies that, for any classifier *h*, the bound

$$\left|\hat{R}_n(h) - R(h)\right| \leq \sqrt{\frac{\log(2/\delta)}{2n}}$$

holds with probability $1 - \delta$.

• If \mathcal{H} is a finite family, i.e., $\mathcal{H} = \{h_1, \dots, h_M\}$, then with probability $1 - \delta/M$ the bound

$$\left|\hat{R}_{n}(h_{j})-R(h_{j})\right|\leq\sqrt{rac{\log(2M/\delta)}{2n}}$$

holds.

Maximal inequality

• The event that $\max_j |\hat{R}_n(h_j) - R(h_j)| > t$ is the union of the events $|\hat{R}_n(h_j) - R(h_j)| > t$ for j = 1, ..., M, so the union bound immediately implies that

$$\max_{j} \left| \hat{R}_{n}(h_{j}) - R(h_{j}) \right| \leq \sqrt{\frac{\log(2M/\delta)}{2n}}$$

with probability $1 - \delta$.

• The logarithmic dependence on *M* implies that we can increase the size of the family *H* exponentially quickly with *n* and maintain the same guarantees on our estimate.

- Assume $|\mathcal{H}| = M$.
- Let \hat{h} be

$$\hat{h} \in \underset{h \in \mathcal{H}}{\operatorname{argmin}} \hat{R}_n(h)$$

• Let \bar{h} be

 $\bar{h} \in \underset{h \in \mathcal{H}}{\operatorname{argmin}} R(h).$

Theorem The estimator \hat{h} satisfies

$$R(\hat{h}) \leq R(\bar{h}) + \sqrt{rac{2\log(2M/\delta)}{n}}$$

with probability at least $1 - \delta$.

 $(\ensuremath{^*})$ It can be shown that

$$\mathbb{E}[R(\hat{h})] \le R(\bar{h}) + \sqrt{\frac{2\log(2M)}{n}}$$

Proof

From the definition of \hat{h} , we have $\hat{R}_n(\hat{h}) \leq \hat{R}_n(\bar{h})$, which gives $R(\hat{h}) \leq R(\bar{h}) + \left[\hat{R}_n(\bar{h}) - R(\bar{h})\right] + \left[R(\hat{h}) - \hat{R}_n(\hat{h})\right]$

The only term here that we need to control is the second one, but since we don't have any real information about \bar{h} , we will bound it by a maximum over \mathcal{H} and then apply Hoeffding:

$$\left[\hat{R}_{n}(\bar{h}) - R(\bar{h})\right] + \left[R(\hat{h}) - \hat{R}_{n}(\hat{h})\right]$$
$$\leq 2\max_{j} \left|\hat{R}_{n}(h_{j}) - R(h_{j})\right| \leq 2\sqrt{\frac{\log(2M/\delta)}{2n}}$$

with probability at least $1-\delta$, which completes the proof.