

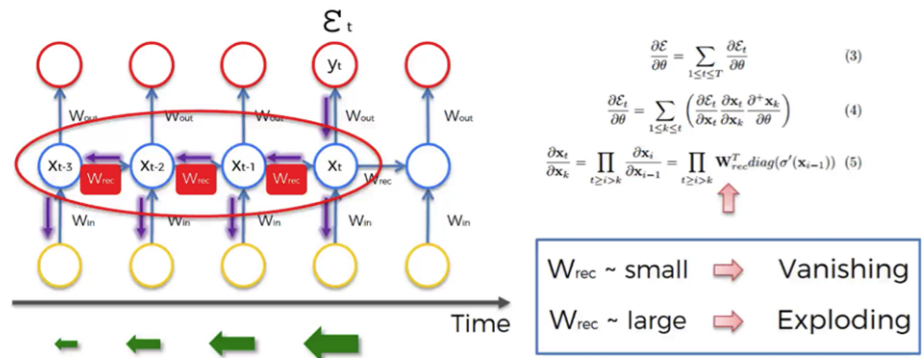
Long Short-Term Memory (LSTM)

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Seoul National University

Young rae Cho

Problem of RNN



- Long-term dependency problem

Problem of RNN

$$|f'_{l_m}(net_{l_m}(t-m))w_{l_m l_{m-1}}|$$

- $net_{l_m}(t-m)$

the aggregated input received by neuron l at time $t-m$.

- $f'_{l_m}(net_{l_m}(t-m))$

the derivative of the activation function f at neuron l in layer m .

- $w_{l_m l_{m-1}}$

the weight of the connection from neuron l in layer $m-1$ to neuron l in layer m

Problem of RNN

- $|f'_{l_m}(\text{net}_{l_m}(t - m))w_{l_m l_{m-1}}| > 1.0$

: gradient exploding problem

- $|f'_{l_m}(\text{net}_{l_m}(t - m))w_{l_m l_{m-1}}| < 1.0$

: gradient vanishing problem

Naïve approach of avoiding gradient vanishing

- A single Unit

$$\vartheta_j(t) = f'_j(\mathit{net}_j(t))\vartheta_j(t+1)w_{jj}.$$

$$f'_j(\mathit{net}_j(t))w_{jj} = 1.0.$$

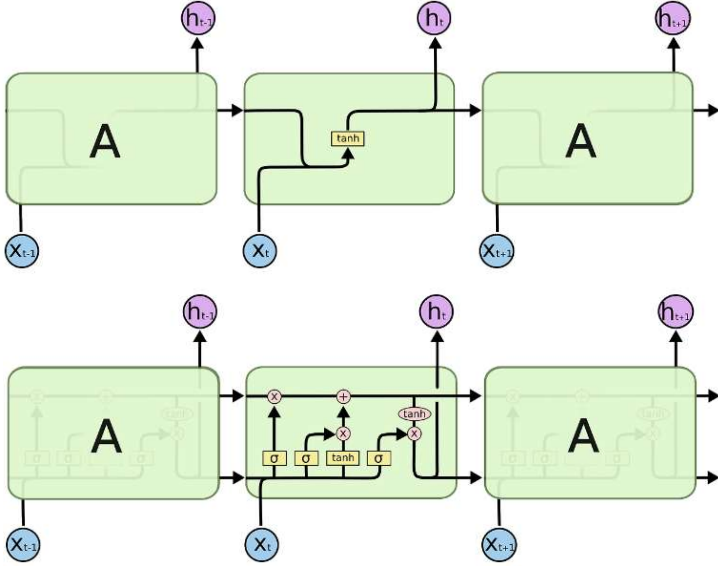
- The Constant Error Carousel (CEC)

$$f_j(\mathit{net}_j(t)) = \frac{\mathit{net}_j(t)}{w_{jj}}$$

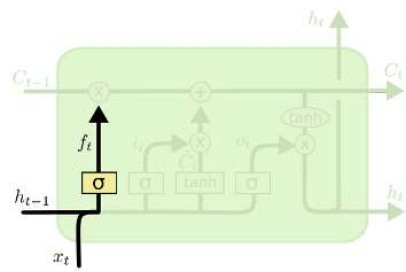
$$y_j(t+1) = f_j(\mathit{net}_j(t+1)) = f_j(w_{jj}y^j(t)) = y^j(t).$$

$$f_j(x) = x, \forall x, \text{ and by setting } w_{jj} = 1.0.$$

The concept of LSTM



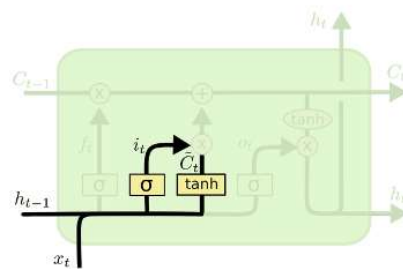
The concept of LSTM



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

LSTM forget gate layer

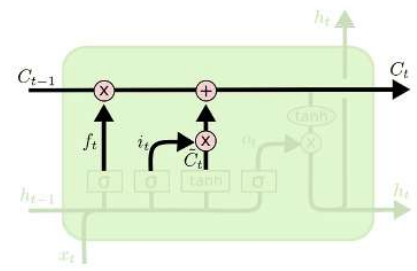
The concept of LSTM



$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

LSTM의 input gate layer

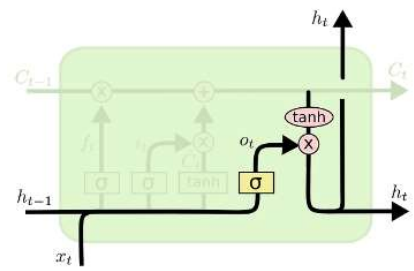
The concept of LSTM



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

LSTM의 cell state 업데이트

The concept of LSTM



$$o_t = \sigma(W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

LSTM output gate layer

Advantages of LSTM

- Long Time Lags
- Generalization
- Parameter Robustness
- Computational efficiency

Limitation of LSTM

- Delayed XOR Problem

[0, 1, 0, 0....., 1, 0]

- Very long sequences
- Counting Discrete Time Steps

Reference

<https://www.superdatascience.com/blogs/recurrent-neural-networks-rnn-the-vanishing-gradient-problem>

<https://dgkim5360.tistory.com/entry/understanding-long-short-term-memory-lstm-kr>